



MTConnect Standard

Part 2 – Components and Data Items

Version 1.0.1

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MTConnect Specification

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1 Overview

2 MTConnect is a standard based on an open protocol for data integration. MTConnect is not
3 intended to replace the functionality of existing products, but it strives to enhance the data
4 acquisition capabilities of devices and applications and move toward a plug-and-play
5 environment to reduce the cost of integration.

6 MTConnect is built upon the most prevalent standards in the manufacturing and software
7 industry, maximizing the number of tools available for its implementation and providing the
8 highest level of interoperability with other standards and tools in these industries.

9 To facilitate this level of interoperability, a number of objectives are being met. Foremost is the
10 ability to transfer data via a standard protocol which includes:

- 11 • A device identity (i.e. model number, serial number, calibration data, etc.).
- 12 • The identity of all the independent components of the device.
- 13 • Possibly a device's design characteristics (i.e. axis length, maximum speeds, device thre-
14 sholds, etc.).
- 15 • Most importantly, data captured in real or near-real-time (i.e. current speed, position data,
16 temperature data, program block, etc.) by a device that can be utilized by other devices or
17 applications (e.g. utilized by maintenance diagnostic systems, management production in-
18 formation systems, CAM products, etc.).

19
20 The types of data that may need to be addressed in MTConnect could include:

- 21 • Physical and actual device design data
- 22 • Measurement or calibration data
- 23 • Near-real-time data from the device

24
25 To accommodate the vast amount of different types of devices and information that may come
26 into play, MTConnect will provide a common high-level vocabulary and structure.

27 The first version of MTConnect will focus on a limited set of the characteristics mentioned
28 above that were selected based on the fact that they can have an immediate affect on the
29 efficiency of operations.

30 1.1 MTConnect Document Structure

31 The MTConnect specification is subdivided using the following scheme:

- 32 Part 1: Overview and Protocol
- 33 Part 2: Components and Data Items
- 34 Part 3: Streams, Events and Samples

35
36 Extensions to the standard will be made according to this scheme and new sections will be
37 added as new areas are addressed. Documents will be named as follows:

38 MTC_Part_<Number>_<Description>.doc. All documents will be developed in Microsoft®
39 Word format and released in Adobe® PDF format. For example, this document is
40 MTC_Part_1_Overview.doc.

41 2 Purpose of This Document

42 This document is intended to:

- 43 • define the MTConnect standard;
- 44 • specify the requirements for compliance with the MTConnect standard;
- 45 • provide engineers with sufficient information to implement *Agents* for their devices;
- 46 • provide developers with the necessary guidelines to use the standard to develop applications.

47 Part 2 of the MTConnect standard focuses on structure and description of what information is
 48 available from the device. The actual device state is not provided in this section, but is covered in
 49 Part 3 covering streams, samples, and events. The descriptive data is similar to the schema of the
 50 data, it describes the components available in this devices and what data items are provided by
 51 each component.

52 This part also covers instructions on how a machine tool should be modeled, the structure of the
 53 component hierarchy, the names for each component (if restricted), and allowable data items for
 54 each of the component. Some components, like Linear axis, use the naming conventions as laid
 55 out in this document. This allows for a consistent meaning across devices.

56 2.1 Terminology

57	Adapter	An optional software component that connects the Agent to the Device.
58 59	Agent	A process that implements the MTConnect specification, acting as an interface to the device.
60 61	Alarm	An alarm indicates an event that requires attention and indicates a deviation from normal operation.
62 63	Application	A process or set of processes that access the MTConnect <i>Agent</i> to perform some task.
64 65 66	Attribute	A part of an element that provides additional information about that element. For example, the name element of the Device is given as <code><Device name="mill-1">...</Device></code>
67 68	CDATA	The text in a simple content element. For example, <i>This is some text</i> , in <code><mt:Alarm ...>This is some text</mt:Alarm></code> .
69 70	Component	A part of a device that can have sub-components and data items. A component is a basic building block of a device.
71 72 73	Controlled Vocabulary	The value of an element or attribute is limited to a restricted set of possibilities. Examples of controlled vocabularies are country codes: US, JP, CA, FR, DE, etc...
74 75 76	Current	A snapshot request to the <i>Agent</i> to retrieve the current values of all the data items specified in the path parameter. If no path parameter is given, then the values for all components are provided.

77	Data Item	A data item provides the descriptive information regarding something that can
78		be collected by the <i>Agent</i> .
79	Device	A piece of equipment capable of performing an operation. A device is
80		composed of a set of components that provide data to the application. The
81		device is a separate entity with at least one Controller managing its operation.
82	Discovery	Discovery is a service that allows the application to locate <i>Agents</i> for devices
83		in the manufacturing environment. The discovery service is also referred to as
84		the <i>Name Service</i> .
85	Element	An XML element is the central building block of any XML Document. For
86		example, in MTConnect the Device element is specified as <code><Device</code>
87		<code>>...</Device></code>
88	Event	An event represents a change in state that occurs at a point in time. Note: An
89		event does not occur at predefined frequencies.
90	HTTP	Hyper-Text Transport Protocol. The protocol used by all web browsers and
91		web applications.
92	Instance	When used in software engineering, the word <i>instance</i> is used to define a
93		single physical example of that type. In object-oriented models, there is the
94		class that describes the thing and the instance that is an example of that thing.
95	LDAP	Lightweight Directory Access Protocol, better known as Active Directory in
96		Microsoft Windows. This protocol provides resource location and contact
97		information in a hierarchal structure.
98	MIME	Multipurpose Internet Mail Extensions. A format used for encoding multipart
99		mail and http content with separate sections separated by a fixed boundary.
100	Probe	A request to determine the configuration and reporting capabilities of the
101		device.
102	REST	REpresentational State Transfer. A software architecture where the client and
103		server move through a series of state transitions based solely on the request
104		from the client and the response from the server.
105	Results	A general term for the <code>Samples</code> and <code>Events</code> contained in a
106		<code>ComponentStream</code> as a response from a <code>sample</code> or <code>current</code> request.
107	Sample	A sample is a data point from within a continuous series of data points. An
108		example of a <code>Sample</code> is the position of an axis.
109	Socket	When used concerning interprocess communication, it refers to a connection
110		between two end-points (usually processes). Socket communication most
111		often uses TCP/IP as the underlying protocol.
112	Stream	A collection of events and samples organized by devices and components.

113	Service	An application that provides necessary functionality.
114	Tag	Used to reference an instance of an XML element.
115	TCP/IP	TCP/IP is the most prevalent stream-based protocol for interprocess
116		communication. It is based on the IP stack (Internet Protocol) and provides the
117		flow-control and reliable transmission layer on top of the IP routing
118		infrastructure.
119	URI	Universal Resource Identifier. This is the official name for a web address as
120		seen in the address bar of a browser.
121	UUID	Universally unique identifier.
122	XPath	XPath is a language for addressing parts of an XML Document. See the XPath
123		specification for more information. http://www.w3.org/TR/xpath
124	XML	Extensible Markup Language. http://www.w3.org/XML/
125	XML Schema	The definition of the XML structure and vocabularies used in the XML
126		Document.
127	XML Document	An instance of an XML Schema which has a single root element and conforms
128		to the XML specification and schema.

129 2.2 XML Terminology

130 In the document there will be references to XML constructs, including elements, attributes,
 131 CDATA, and more. XML consists of a hierarchy of elements. The elements can contain sub-
 132 elements, CDATA, or both. For this specification, however, an element never contains mixed
 133 content or both sub-elements and CDATA. Attributes are additional information associated with
 134 an *element*. The textual representation of an element is referred to as a *tag*. In the example:

```
135 <Foo name="bob">Ack!</Foo>
```

136 an *element* consists of a named opening and closing tag. In the above example, `<Foo . . . >` is
 137 referred to as the opening tag and `</Foo>` is referred to as the closing tag. The text `Ack!` in
 138 between the opening and closing tags is called the CDATA. CDATA can be restricted to certain
 139 formats, patterns, or words. In the document when it refers to an element having CDATA, it
 140 indicates that the element has no sub-elements and only contains data.

141 When one looks at an XML Document there are two parts. The first part is typically referred to
 142 as an XML declaration and is only a single line. It looks something like this:

```
143 <?xml version="1.0" encoding="UTF-8"?>
```

144 This line indicates the XML version being used and the character encoding. Though it is possible
 145 to leave this line off, it is usually considered good form to include this line in the beginning of
 146 the document. The second part contains the XML document and consists of the rest of the
 147 document.

148 Every XML Document contains one and only one root element. In the case of MTConnect, it is
 149 the MTConnectDevices, MTConnectStreams, or MTConnectError element. When
 150 these root elements are used in the examples, you will sometimes notice that it is prefixed with
 151 mt: as in mt:MTConnectDevices. The mt: is what is referred to as a namespace. In XML,
 152 to allow for multiple XML Schemas to be used within the same XML Document, a namespace
 153 will indicate which XML Schema is in effect for this section of the document. This convention
 154 allows for multiple XML Schemas to be used within the same XML Document, even if they have
 155 the same element names. The namespace is optional and is only required if multiple schemas are
 156 required.

157 An *attribute* is additional data that can be included in each XML element. For example, in the
 158 following MTConnect DataItem, there are several attributes describing the data item:

```
159 1. <DataItem name="Xpos" type="POSITION" subType="ACTUAL" category="SAMPLE" />
```

160 The name, type, subType, and category are attributes of the element. Each attribute can
 161 only occur once within an element declaration, and it can either be required or optional.

162 An element can have any number of sub-elements. The XML Schema specifies which sub-
 163 elements and how many times a given sub-element can occur. Here's an example:

```
164 1. <TopLevel>
165 2.   <FirstLevel>
166 3.     <SecondLevel>
167 4.       <ThirdLevel name="first"></ThirdLevel>
168 5.       <ThirdLevel name="second"></ThirdLevel>
169 6.     </SecondLevel>
170 7.   </FirstLevel>
171 8. </TopLevel>
```

172 In the above example, the FirstLevel has a sub-element SecondLevel which in turn has
 173 two sub-elements, ThirdLevel, with different names. Each level is an element and its children
 174 are its sub-elements and so forth.

175 An XML Document can be validated. The most basic check is to make sure it is well-formed,
 176 meaning that each element has a closing tag, as in <foo> . . . </foo> and the document does
 177 not contain any illegal characters (<>) when not specifying a tag. If the closing </foo> was left
 178 off or an extra > was in the document, the document would not be well-formed and may be
 179 rejected by the receiver. The document can also be validated against a schema to ensure it is
 180 valid. This second level of analysis checks to make sure that required elements and attributes are
 181 present and only occur the correct number of times. A valid document must be well-formed.

182 All MTConnect documents must be valid and conform to the XML Schema provided along with
 183 this specification. The schema will be versioned along with this specification. The greatest
 184 possible care will be taken to make sure that the schema is backward compatible.

185 For more information, visit the w3c website for the XML Standards documentation:

186 <http://www.w3.org/XML/>

187 2.3 Markup Conventions

188 MTConnect follows industry conventions on tag format and notations when developing the XML
189 schema. The general guidelines are as follows:

- 190 1. All tag names will be specified in Pascal case (first letter of each word is capitalized). For
191 example: <ComponentEvents />
- 192 2. Attribute names will also be camel case, similar to Pascal case, but the first letter will be
193 lower case. For example: <MyElement attributeName="bob"/>
- 194 3. All values that are part of a limited or controlled vocabulary will be in upper case. For
195 example: ON, OFF, ACTUAL, etc...
- 196 4. Dates and times will follow the W3C ISO 8601 format with arbitrary fractions of a
197 second allowed. Refer to the following specification for details:
198 <http://www.w3.org/TR/NOTE-datetime> The format will be YYYY-MM-
199 DDThh:mm:ss.ffff, for example 2007-09-13T13:01.213415. The accuracy and number of
200 fractional digits of the timestamp is determined by the capabilities of the device collect-
201 ing the data. All times will be given in UTC (GMT).
- 202 5. Element names will be spelled-out and abbreviations will be avoided. The one exception
203 is the word `identifier` that will be abbreviated `Id`. For example:
204 `SequenceNumber` will be used instead of `SeqNum`.

205 2.4 Document Conventions

206 The following documentation conventions will be used in the text:

- 207 • The word **MUST** is used to indicate provisions that are mandatory. Any deviation from those
208 provisions will not be permitted.
- 209 • The word **SHOULD** is used to indicate a provision that is recommended but the exclusion of
210 which will not invalidate the implementation.
- 211 • The word **MAY** will be used to indicate provisions that are optional and are up to the imple-
212 mentor to decide if they are relevant to their device.

213 In the tables where elements are described, the Occurrence column indicates if the attribute or
214 sub-elements are required by the specification.

215 For attributes:

- 216 1. If the Occurrence is 1, the attribute **MUST** be provided.
- 217 2. If the Occurrence is 0..1, the attribute **MAY** be provided, and at most one occurrence of
218 the attribute may be given.

219
220 For elements:

- 221 1. If the Occurrence is 1, the element **MUST** be provided.
- 222 2. If the Occurrence is 0..1, the element **MAY** be provided, and at most one occurrence of
223 the element may be given.
- 224 3. If the Occurrence is 1..INF, one or more elements **MUST** be provided.

225 4. If the Occurrence is a number, e.g. 2, exactly that number of elements **MUST** be pro-
 226 vided.

227
 228 Font styles used:

229 Code samples as well as any XML elements or attributes will always be given in fixed
 230 width fonts. References to other *Documents* or *Sections* will be presented in italics.

231 2.5 Units

232 MTConnect will adopt the units common to most standards specifications for exchanging data
 233 items. This will allow for greatest interoperability with other specifications. It is assumed that all
 234 MTConnect *Agents* will be responsible for converting the units from the native device units.

Property	Symbol	Unit
Angle	°	decimal degrees
Angular Acceleration	°/s ²	degree per second square
Angular Velocity	°/s	degrees per second
Elapsed time	s	seconds with fractions
Force	N	newtons
Length	mm	millimeters
Linear Acceleration	mm/s ²	millimeter per second square
Linear Velocity	mm/s	millimeters per second
Mass	kg	kilograms
Spindle Speed	rev/min	revolutions per minute
Temperature	°C	degree Celsius

235 Additional units will be added as needed. The decision to require the *Agent* to convert to the
 236 standard simplifies the applications and will provide greater interoperability and accuracy.

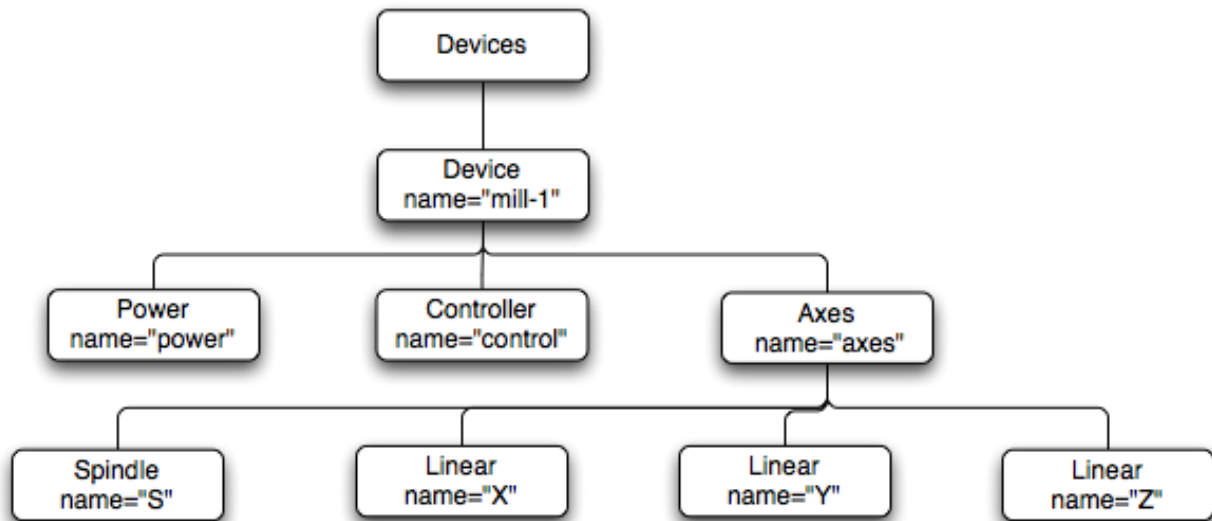
237 2.6 Referenced Standards and Specifications

238 A large number of specifications are being used to normalize and harmonize the schema and the
 239 vocabulary (names of tags and attributes) specified in MTConnect (*See Bibliography for*
 240 *complete references*).

241 3 Devices and Components

242 A device can be thought of as a group of components. For example, the Device is a three axis
 243 mill. The mill has components, one of the components is a Power component, often thought of
 244 as the main power supply. The mill also has sub-components of the Axes component; these are
 245 the three Linear axes and a Spindle. The Controller component controls the axes and
 246 runs the program. These are all sub-components of the Device.

247 For example, this three axis mill is modeled as a device that has a power supply, a controller,
 248 three linear axes and one spindle:



249

250 **Figure 1: Example Devices Structure**

251 Multiple devices may be represented in a top level container element called Devices. These
 252 container elements have no additional attributes and are only used to group sub-elements
 253 together. There are three containers used in the MTConnectDevices document. The first is
 254 the Devices element that contains all Device elements. The next container is the
 255 Components container that groups all the subcomponents together, like the Axes, Spindle,
 256 and Controller. The last container is the DataItems container that groups all data items
 257 for a component together.

258 In the following document structure:

```

259   MTConnectDevices
260     Devices
261       Device
262         Components
263           Axes
264             Components
265               Spindle [S]
266               Linear [X]
267                 DataItems
268                   DataItem [Xpos]
  
```

```

269
270         Controller
271             DataItems
272                 DataItem [mode]
273                 DataItem [execution]

```

274 These containers make it easier to address individual parts of the XML document. For example,
 275 if one wanted to retrieve just the DataItems for the Controller you can express this using
 276 the following XPath: //Controller/DataItems/*. If you were interested in retrieving
 277 only the subcomponents of the Axes component, you would write the following XPath:
 278 //Axes/Components/*.

279 All Devices, Components, and DataItems require an id attribute. The id attribute must adhere to
 280 the w3c standard ID-type and must be unique for the entire in an XML document. The id
 281 attributes **MUST** start with a :, _, or letter (A-Z, a-z) and then may be followed with numbers,
 282 letters, -, or a period (.). For more information see: <http://www.w3.org/TR/REC-xml/#NT-Name>.
 283

284 3.1 Devices

285 The Devices element is a top level container for all Devices that is returned from a probe
 286 request. The probe response will only return an XML document that is a valid
 287 MTConnectDevices document.

Elements	Description	Occurrence
Device	The root of each device. The Device is contained within the top level Devices container. There can be multiple Device elements.	1..INF

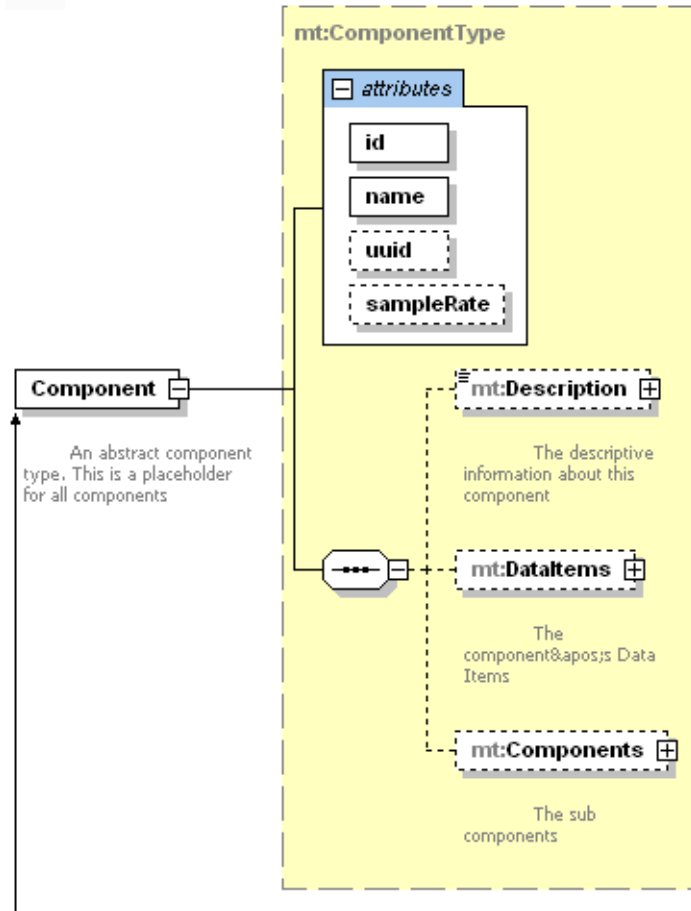
288

289 3.2 Component

290 The Agent needs to be capable of delivering data associated with each component to an
 291 application. The description of these pieces of information is referred to as DataItems and will
 292 be discussed in the section 4 of this document. The actual values for those data items are
 293 delivered in Streams and will be discussed in Part 3 of the standard on Streams, Samples, and
 294 Events.

295

296 **3.3 Component Schema**



297

298

Figure 2: Component Schema

299 **3.3.1 Common Component Attributes**

300 Every component has the following composition:

Attribute	Description	Occurrence
uuid	A unique identifier that will only refer to this component. For example, this can be the manufacturer code and the serial number. The uuid should be alphanumeric and not exceeding 255 characters.	0..1*
name	The name of the component. This name should be unique within the machine to allow for easier data integration.	1
id	The unique identifier for this component in the document. An id must be unique across all the id attributes in the document. An XML ID-type.	1

Attribute	Description	Occurrence
sampleRate	The rate in seconds that data is obtained from the component. This is the number of milliseconds between data captures. If the sample rate is smaller than one millisecond, the number can be represented as a floating point number. For example, for one 100 microsecond sample rate would be 0.1.	0..1**

301
 302 Notes: * The uuid **MUST** be provided for the Device, it is optional for all other components.
 303 ** The sampleRate is used to aid the application in interpolating values. This is the
 304 desired sample rate and may vary depending on the capabilities of the device.

305 **3.3.2 Component Elements**

Element	Description	Occurrence
Description	An element that can contain any descriptive content. This can contain configuration information and manufacturer specific details.	0..1
Components	Sub-components of this component.	0..1*
DataItems	The data items this component provides. The data items are descriptions of the data events for reporting.	0..1*

306
 307 Notes: *At least one of Components or DataItems **MUST** be provided.

308 **3.3.2.1 Description**

Attribute	Description	Occurrence
manufacturer	The name of the manufacturer of the component	0..1
serialNumber	The device's serial number	0..1
station	The station the device is located at. When a device is part of a manufacturing unit or cell with multiple stations that share the same physical controller.	0..1

309
 310 The CDATA of the Description is any additional descriptive information the implementor
 311 chooses to include regarding the component.

312 **3.3.2.2 Components**

Element	Description	Occurrence
Component	One or more components. This can also include the subtypes of Component like Axes, Linear, Power, Thermostat, etc...	1..INF

313

314 **3.3.2.3 DataItems**

Element	Description	Occurrence
DataItem	Only elements of types DataItem can be specified	1..INF

315

316 **3.4 Types of Components**

317 All the elements in Figure 1 on page 8 are subtypes of Component. A component is an abstract
 318 type that allows for extensibility. As the specification progresses, more component types will be
 319 added, like Joint (for robotics) and Tool (for presetter).

320 **3.4.1 Device**

321 At the top of the component tree there **MUST** be the root element Device. A Device is a
 322 container that holds all the components associated with this piece of equipment. The Device
 323 **MUST** have an alarm data item that provides a place for all Device general alarms that cannot
 324 be assigned to a sub-component.

325 **3.4.1.1 Device Attributes**

Attribute	Description	Occurrence
iso841Class	The ISO 841 classification for the device.	1

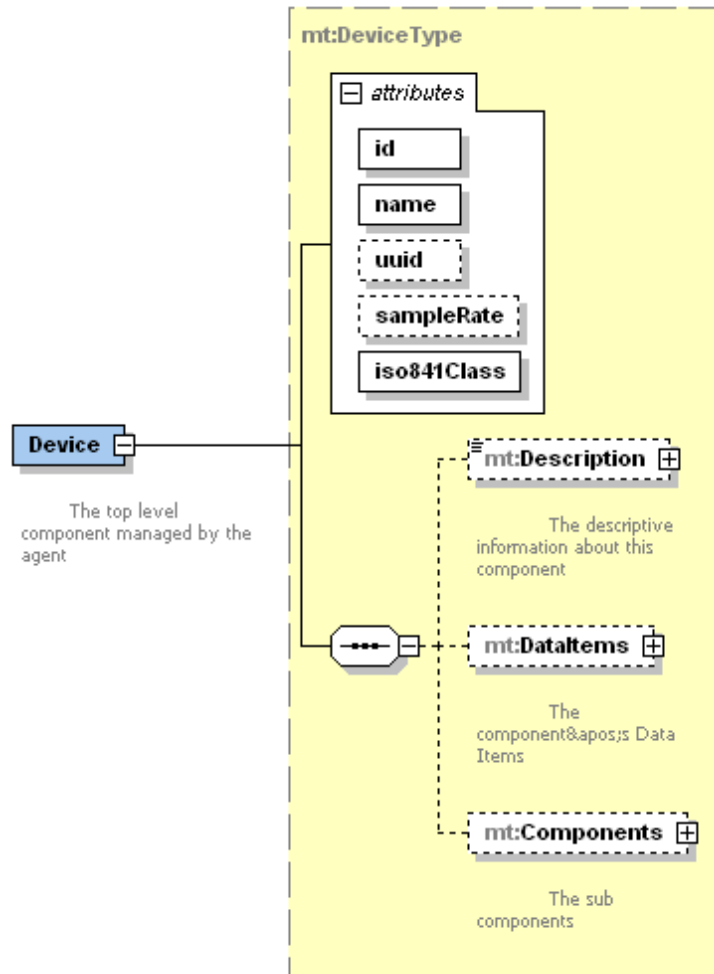
326

327 A device **MUST** be classified using one of the following identifiers from the ISO 841
 328 specification. The following classification is taken from the appendix of the ISO 841
 329 specification, please use the diagram that best matches the figures in the appendix of ISO 841. If
 330 there is no diagram that matches the device, use `iso841Class="1"`. Please provide us with a
 331 diagram of your device and its respective components and we will attempt to create a new
 332 classification for the device.

MTC ISO 841 Classification	Description	Figure
1	Other (Device not included in list)	
2	Parallel lathe (engine lathe)	A.2
3	Twin turret lathe with programmable tailstock	A.3
4	Vertical turning and boring lathe	A.4
5	Milling machine with horizontal spindle	A.5
6	Milling machine with vertical spindle (with W axis)	A.6
7	Boring and milling machine with horizontal spindle	A.7
8	Milling machine with vertical spindle	A.8

MTC ISO 841 Classification	Description	Figure
9	Portal-type milling machine	A.9
10	Gantry-type milling machine	A.10
11	Planer-type horizontal boring machine	A.11
12	Profile and contouring milling machine with movable table	A.12
13	Profile and contour milling machine with horizontal spindle	A.13
14	Profile and contour milling machine with tilting head	A.14
15	Profile and contour milling machine with tilting table	A.15
16	External cylindrical grinding machine	A.16
17	Tool and cutter grinding machine	A.17
18	Openside planer	A.18
19	Vertical filament winding machine	A.19
20	Horizontal filament winding machine	A.20
21	Flame cutting machine	A.21
22	Punch press	A.22
23	Drafting machine	A.23
24	Right-hand tube bender	A.24
25	Surface grinding machine with vertical grinding wheel	A.25
26	Cavity sinking EDM machine	A.26
27	Surface grinding machine	A.27
28	Coordinate measuring machine	A.28
29	Press brake	A.29
30	Wire electrical discharge machine	A.30
31	Laser cutting machine	A.31
32...	Reserved for future use.	

334 **3.4.1.2 Device Structure**



335

336

Figure 3: Device Schema Diagram

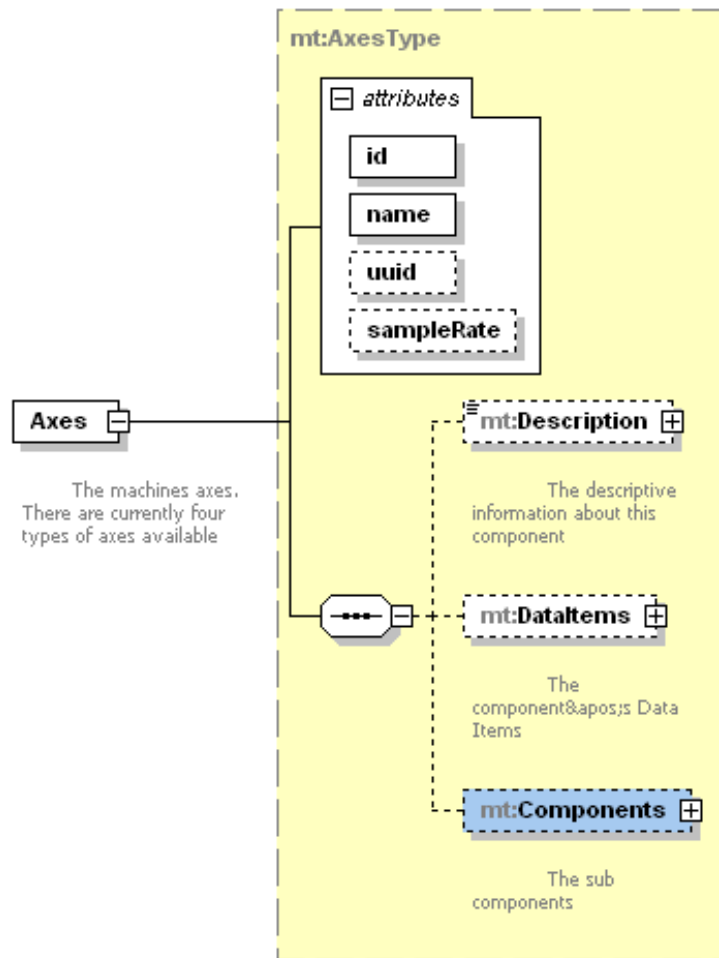
337 **3.4.2 Axes**

338 There can be an arbitrary number of axes. This flexibility will accommodate the more complex
 339 multi-axis, multi-spindle machines in the future. An *Axis* can be one of three different types:
 340 Linear, Rotary, and Spindle. The Linear axes **MUST** be named X, Y, Z and U, V, W as
 341 defined in the ISO-841-2001 specification. Rotary axes **MUST** be named as A, B, and C and
 342 rotate around the Linear X, Y, and Z axes respectively as defined in ISO-841-2001.

343 When a device has an axis that serves two purposes, such as a rotational axis that can become a
 344 spindle, this **MUST** be modeled as two separate axis. The first axis will be a Spindle where the
 345 name will be “S” and the second axis will be a Rotary axis with the name “C”. At any time only
 346 one of the two axes will be active. (Note: we need to have a way to determine which is active at
 347 any given time.)

348 *Note:* The convention to be used for multiple linear, rotary, and spindle axes having the same
 349 designation is to index the letter with a number. For this standard the number starts at 2 (i.e. X,

350 X2, X3, ... or S, S2, S3, S4, ...). This is in compliance with the ISO-841-2001. Please refer to
 351 that specification for more details.

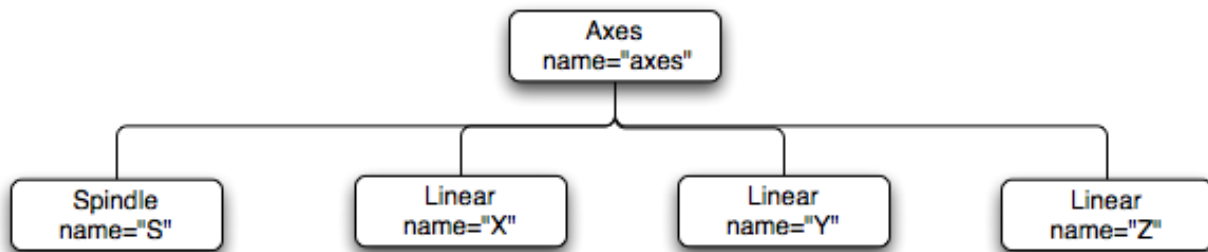


352

353

Figure 4: Axes Schema Diagram

354 The Axes component **MUST** contain at least one Axis component. The possible axis
 355 components are as follows:



356

357

Figure 5: Axes Example With Three Linear Axes and one Spindle

358

359 **Linear** A linear axis moves in the direction parallel to the motion direction of a
 360 linearly moving component. Because of various errors, the direction of the
 361 linear axis can best be defined as a least-squared fit of a straight line to the
 362 appropriate straightness data.

363 **Rotary** An axis whose function is to provide rotary motion either for the purposes of
 364 positioning and can be used for continuous-path contour cutting in a rotary
 365 direction or for repositioning different faces of the part for the purpose of
 366 metal removal.

367 **Spindle** Device that provides an axis of rotation for the purpose of rapidly rotating a
 368 part or a tool to provide sufficient surface speed for cutting operations.

369 **3.4.3 Controller**

370 The `Controller` component represents the CNC (Computer Numerical Control) or PAC
 371 (Programmable Automation Control) which has been referred to as a *Motion Control* or *General*
 372 *Purpose Motion Control*. The `Control` provides information regarding the execution of a control
 373 program and the execution state of the device. There are no required sub-components of the
 374 `Controller`.

375 For more complex devices and controllers, it has been considered splitting out the individual
 376 execution program for each channel. This may require multiple `Control` components of a
 377 single device associated with specific axes. The modeling will be deferred to later revisions of
 378 the standard.

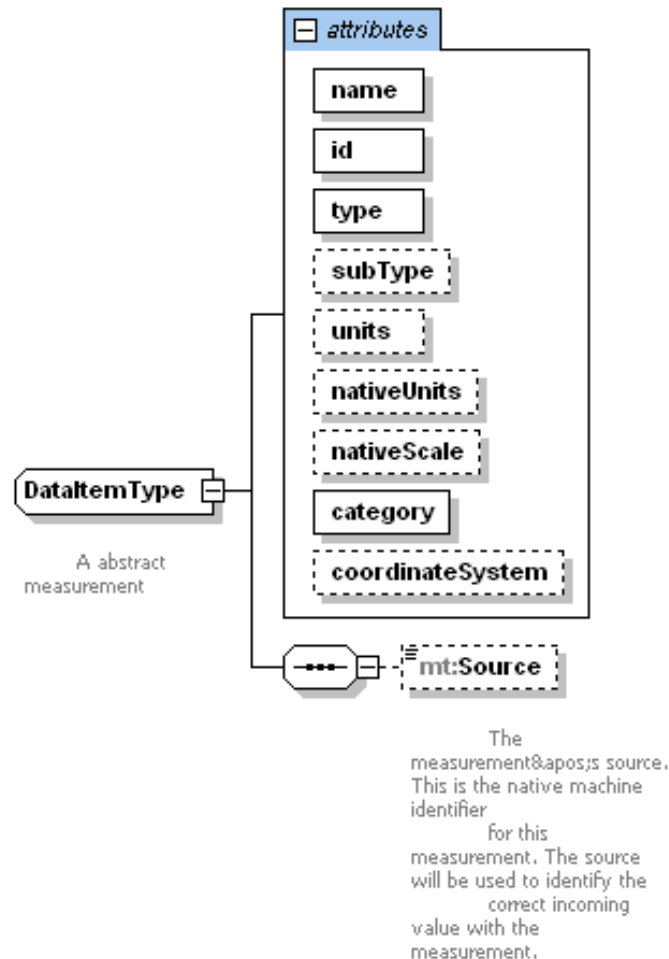
379 **3.4.4 Power**

380 The `Power` component is provided to report on the power status and possibly the voltage
 381 associated with its parent component. The device **MUST** contain a power component and **MUST**
 382 only contain the `POWER_STATUS` (on/off status). Any other data items **MAY** be added. Any
 383 other component, such as a spindle, that can be switched on or off separately from the `Device`
 384 **SHOULD** have a power component. There are no sub-components of `Power`.

385 `Power` **MUST** only be set to on if the device is reachable and its power indicator is on. If the
 386 device is unreachable from the *Agent*, it **MUST** be considered `OFF`. `OFF` is defined as the power
 387 to any other component than the computer controller is disconnect from the power supply.

388 4 Data Items

389 A `DataItem` describes a piece of information that can be collected from a component. The data
 390 item **MUST** specify the `type` of data being collected, the name of the data item, and the
 391 category of the item. There will only be one category for each `type`, but it **MUST** be
 392 included to aid the application in determining the location for the data stream. The data item
 393 **MAY** specify a `Source` sub-element to provide the native name for the data feed.



394

395

Figure 6: DataItem Schema Diagram

396 A `DataItem` **MAY** also specify the `subType`, to further qualify the type of data being
 397 requested. Subtypes are required for certain data items. For example, the `POSITION` has two
 398 subtypes: `ACTUAL` and `COMMANDED`. These are two separate data items that can be reported
 399 independently. See section 4.2.1 for a complete list of `type/subtype` relations.

400 The `units` **MUST** be specified for any numeric data type. The `nativeUnits` **MAY** be
 401 specified if they apply to the type of data and if they differ from the `units`. The `Agent` is
 402 responsible for converting the `nativeUnits` to the `units` before sending them to the

403 applications. In addition, `nativeUnits` **MAY** be scaled using the `nativeScale` attribute;
 404 for example, if the device measures velocity in 100 ft/min, MTCConnect would represent it with
 405 the following attributes: `nativeUnits="FEET/MINUTE"` and `nativeScale="100"`.

406 4.1 DataItem Element

407 4.1.1 Data Item Attributes

Attribute	Description	Occurrence
<code>id</code>	The unique identifier for this data item. The <code>id</code> attribute must be unique across the entire document including the <code>ids</code> for components. An XML ID-type.	1
<code>name</code>	The name of the data item. A data item will have a unique name within the component. If there are multiple data items of the same type, like <code>Position</code> , the name will distinguish the data item.	1
<code>type</code>	The type of data being measured. Examples of types are <code>POSITION</code> , <code>VELOCITY</code> , <code>ANGLE</code> , <code>CODE</code> , <code>BLOCK</code> , <code>SPINDLE SPEED</code> , etc. The types are part of a controlled vocabulary that is fixed version 1.0.	1
<code>subType</code>	A sub-categorization of the data item type. Examples of position subtypes of <code>POSITION</code> are <code>ACTUAL</code> and <code>COMMANDED</code> . Not all types have subtypes and this can be left off. The subtypes are part of a controlled vocabulary that is fixed in version 1.0.	0..1
<code>category</code>	This is how the data item will be sampled. The two options are <code>SAMPLE</code> and <code>EVENT</code> .	1
<code>nativeUnits</code>	The native units used by the component. These units will be converted before they are delivered to the application.	0..1
<code>units</code>	The units delivered to the application. These will always be the same for this data item type. This MUST be specified for all numeric values.	0..1
<code>nativeScale</code>	The multiplier for the native units. The received data MAY be divided by this value before conversion. If provided the value MUST be numeric.	0..1
<code>significantDigits</code>	The number of significant digits in the reported value. This is used by applications to determine accuracy of values. This SHOULD be specified for all numeric values.	0..1

Attribute	Description	Occurrence
coordinateSystem	The coordinate system being used.	0..1

408

409 **4.1.2 Data Item Elements**

Element	Description	Occurrence
Source	Source is an optional element that contains the long name of the data item if it is too complex for the name attribute. For example, if the data item has the name Xact and the axis position is delivered as Axis.channel.0.position from the device. The name attribute is Xact and the source is Axis.channel.0.position. If the source is not specified, it will be assumed to be the same as the name.	0..1

410

411

412 **4.1.3 Data Item attribute: category**

413 MTConnect provides two different categories of data items, SAMPLE and EVENT. The
 414 category will indicate where the results will be reported in the XML Document as a response
 415 to a sample or current request. See Part 3 section 3 on *Streams, Samples, and Events* for
 416 more information.

417 **SAMPLE** A sample data item has a value that varies between different values in a
 418 manner that can be interpolated. A continuous value can be sampled at any
 419 point-in-time and will always produce a result. An example of a continuous
 420 data item is the S axis spindle speed.

421
 422 Sample data items that are continuous are always scalar floating point or
 423 integers that can have an infinite number of possible values. This is different
 424 from state or discrete data items that have a limited number of possible values.

425 **EVENT** Unexpected or discrete occurrence in a component. This includes state
 426 changes and alarms. Events do not have intermediate values that differ at
 427 intermediate times, as do samples.

428 **4.1.4 Data Item attribute: coordinateSystem**

429 A data item can specify an optional coordinate system that is being used. If not specified, the
 430 coordinates **MUST** be **MACHINE**. The possible values of coordinates are:

431 **MACHINE** An unchangeable coordinate system that has machine zero as its origin.

432 **WORK** The position that acts as the origin for a particular workpiece.

433 **4.1.5 Data Item attribute: units**

Unit	Description
AMPERE	Amps
CELCIUS	Degrees Celsius
COUNT	A counted event
DEGREE	Angle in degrees
DEGREE/SECOND	Degrees per second
DEGREE/SECOND^2	Acceleration in degrees per second squared
HERTZ	Frequency measured in cycles per second
KILOGRAM	Kilograms
LITER	Liters
MILLIMETER	Millimeters
MILLIMETER/SECOND	Millimeters per second
MILLIMETER/SECOND^2	Acceleration in millimeters per second squared
NEWTON	Force in newtons
PASCAL	Pressure in Newtons per square meter
PERCENT	Percent
REVOLUTION/MINUTE	Revolutions per minute
SECOND	A measurement of time.
STATUS	A status that conforms to the data item's controlled vocabulary. Used in events to indicate states or status.
NEWTON_METER	Torque, a unit for force times distance. The SI units will be used.
VOLT	Volts
WATT	Watts

434

435 **4.2 Types and Subtypes of Data Items**

436 What follows is the association between the various types and subtypes of data items. Each data
437 item type **MUST** be translated into a `Sample` or `Event` with the following rules: The type
438 name will be all in capitals with an underscore (`_`) between words. The element of the event or
439 sample will be the transformation of the data item type by capitalizing the first character of each

440 word and then removing the underscore. For example, the data item type POWER_STATUS is
 441 PowerStatus, POSITION is Position, and SPINDLE_SPEED is SpindleSpeed.

442 An example of this transformation between the DataItem name and the Stream element is as
 443 follows:

```
444 <Controller name="Controller" id="8">
445   <DataItems>
446     <DataItem type="LINE" category="EVENT" id="19" subType="ACTUAL"
447       name="line" />
448     <DataItem type="CONTROLLER_MODE" category="EVENT" id="20" name="mode"
449       />
450     <DataItem type="PROGRAM" category="EVENT" id="21" name="program" />
451     <DataItem type="EXECUTION" category="EVENT" id="22" name="execution" />
452     <DataItem type="BLOCK" category="EVENT" id="23" name="block" />
453   </DataItems>
454 </Controller>
```

455 The transformation from the probe (*as defined in Part 1 of the standard*) to the current or
 456 sample will occur as follows. This also illustrates how the subType is also placed in the
 457 ComponentStream as well. The probe will provide the category meaning the sub-
 458 element of the ComponentStream the items will appear in. Also note how the
 459 CONTROLLER_MODE was changed to ControllerMode in the current request below.

```
460 <ComponentStream componentId="8" component="Controller" name="Controller">
461   <Events>
462     <Line dataItemId="19" timestamp="2009-03-04T19:45:50.458305"
463       subType="ACTUAL" name="line" sequence="150651130">702</Line>
464     <Block dataItemId="23" timestamp="2009-03-04T19:45:50.458305"
465       name="block" sequence="150651134">x0.371524 y-0.483808</Block>
466
467     <ControllerMode dataItemId="20" timestamp="2009-02-26T02:02:35.716224"
468       name="mode" sequence="182">AUTOMATIC</ControllerMode>
469   </Events>
470 </ComponentStream>
471
```

472 **4.2.1 Data Item Types for SAMPLE Category**473 The types are given in **bold** and the subtypes are indented and in plain text.

Data Item type/subtype	Description	Units
ACCELERATION	Rate of change of velocity	MILLIMETER/SECOND^2
ANGULAR_ACCELERATION	Rate of change of angular velocity.	DEGREE/SECOND^2
ANGULAR_VELOCITY	Rate of change of angular position.	DEGREE/SECOND
AMPERAGE	The line current	AMPERE
ANGLE	The angular position of a component relative to the parent.	DEGREE
ACTUAL	The angular position as read from the physical component.	DEGREE
COMMANDED	The angular position computed by the controller.	DEGREE
AXIS_FEEDRATE	The feedrate of the axis.	MILLIMETER/SECOND
ACTUAL	The single dimension feedrate.	MILLIMETER/SECOND
COMMANDED	The feedrate as specified in the program.	MILLIMETER/SECOND
OVERRIDE	The operator's overridden value. Percent of commanded.	PERCENT
DISPLACEMENT	The displacement as measured from zero to peak	MILLIMETER
FREQUENCY	The frequency as measure in cycles per second	HERTZ
GLOBAL_POSITION	The position in three-dimensional space. The X, Y, and Z positions will be provided.	MILLIMETER
ACTUAL	The position of the component as read from the device.	MILLIMETER
COMMANDED	The position computed by the controller.	MILLIMETER
LOAD	The load on the component.	NEWTON
PATH_FEEDRATE	The feedrate of the tool path.	MILLIMETER/SECOND
ACTUAL	The three-dimensional feedrate derived from all components.	MILLIMETER/SECOND
COMMANDED	The feedrate as specified in the program	MILLIMETER/SECOND
OVERRIDE	The operator's overridden value. Percent of commanded.	PERCENT

Data Item type/subtype	Description	Units
PRESSURE	The pressure on the component	PASCAL
POSITION	The position of the component. Defaults to machine coordinates.	MILLIMETER
ACTUAL	The position of the component as read from the device.	MILLIMETER
COMMANDED	The position as given by the Controller.	MILLIMETER
SPINDLE_SPEED	The rotational speed of the spindle.	REVOLUTION/MINUTE
ACTUAL	The rotational speed the spindle is spinning at.	REVOLUTION/MINUTE
COMMANDED	The rotational speed the as specified in the program.	REVOLUTION/MINUTE
OVERRIDE	The operator's overridden value. Percent of commanded.	PERCENT
TEMPERATURE	The temperature	CELSIUS
TORQUE	The torque	NEWTON_METER
VELOCITY	The rate of change of position.	MILLIMETER/SECOND
VOLTAGE	The voltage	VOLT
WATTAGE	The wattage	WATT

474

475

476 **4.2.2 Data Item Types for EVENT Category**

477 Note: The Event does not have any units since these values are not scalars.

Data Item type/subtype	Description
BLOCK	The block of code being executed. The block contains the entire expression of the step in the program.
CODE	The programmatic code being executed
PART_COUNT	The current count of parts produced as represented by the controller. Must be an integer value.
ALL	The count of all the parts produced. If the subtype is not given, this is the default.
GOOD	Indicates the count of correct parts made.
BAD	Indicates the count of incorrect parts produced.
DIRECTION	The rotational direction of the Axis. CLOCKWISE or COUNTER_CLOCKWISE
EXECUTION	The execution status of the Controller. READY, ACTIVE, INTERRUPTED, or STOPPED
LINE	The current line of code being executed
POWER STATUS	The ON/OFF status of the component.
PROGRAM	The name of the program being executed
ALARM	An alarm is a special data item that will report any alarm for this component. An alarm MUST be included as a DataItem for the Device
CONTROLLER_MODE	The current controller's mode. AUTOMATIC, MANUAL, or MANUAL_DATA_INPUT

478

479 **5 Component and Data Item Relationships**

480 This section will discuss the association between Component, DataItems, and Events and
 481 Samples. For each component, there are a limited set of allowable sub-components and a
 482 limited set of data items. For example, an Axes component may not have a Device or a
 483 Controller as a child, and it may not have as a Block DataItem type, since it is incapable
 484 of running a program.

485 **5.1 Overview**

486 At the top level, a device **MUST** always contain a Power component as the main power supply.
 487 Every component that is capable of managing its own power supply, **SHOULD** have a Power
 488 sub-component. For example, a spindle **SHOULD** have a Power sub-component if it can be
 489 turned off separately from the device.

490 Any component **MAY** also include an arbitrary set of sensors as sub-components. The sensor is
 491 currently a placeholder for extensible data collection devices and is not modeled in this version
 492 of the specification. A sensor will be an external device that will collect data and report it to the
 493 Agent. The sensor **MUST** be correctly associated with its most relevant component. The rules
 494 governing this association will be covered in a later version of this specification.

495 **5.2 Device**

496 The Device is the only top level element in the component tree. Since an MTConnect Agent
 497 can manage multiple devices, the schema provides a top level container Devices to hold the
 498 Device elements.

499 **5.2.1 DataItem types**

- 500 • ALARM - An alarm placeholder for all alarms that are not associated with another component.

501 **5.2.2 Sub-components of Device**

- 502 • Power
- 503 • Controller
- 504 • Axes

505 **5.3 Common Components and Data Items**

506 **5.3.1 Axes**

507 The Axes component serves two functions: it is a container for the actual axes as well the global
 508 data items for kinematics, path feedrate and other aggregates of all the Axis components below
 509 it. An Axes **MAY** have one or more of these:

510 **5.3.1.1 DataItem types**

- 511 • GLOBAL_POSITION
- 512 • PATH_FEEDRATE
- 513 • ACCELERATION
- 514 • VELOCITY

515 **5.3.1.2 Sub-components of Axes**

- 516 • Linear
- 517 • Rotary
- 518 • Spindle
- 519

520 **5.3.2 Linear**

521 A linear axis represents travel along a straight line. The name of the linear axis **SHOULD** follow
522 the conventions of the industry.

523 **5.3.2.1 DataItem types**

- 524 • POSITION
- 525 • ACCELERATION
- 526 • VELOCITY
- 527 • LOAD
- 528 • AXIS_FEEDRATE

529 **5.3.3 Rotary**

530 A rotary axis revolves around a point.

531 **5.3.3.1 DataItem types**

- 532 • ANGLE
- 533 • ANGULAR_ACCELERATION
- 534 • ANGULAR_VELOCITY
- 535 • LOAD
- 536 • AXIS_FEEDRATE
- 537 • TORQUE

538 **5.3.4 Controller**

539 The controller component is the component that controls a device, executes a program, and sends
540 instructions to the other components of the machine. It is the brains of the machine and can be
541 asked for its current execution state and program name.

542 **5.3.4.1 DataItem types**

- 543 • PROGRAM
- 544 • EXECUTION
- 545 • LINE
- 546 • BLOCK
- 547 • CODE
- 548 • CONTROLLER_MODE
- 549 • PART_COUNT

550 **5.3.5 Power**

551 The power component represents the electrical activation of the component. The data items the
552 power component can collect are a simple status (on/off) and three power related measurements,
553 voltage, amperage and watts. There are no sub-components of Power. The reason for making this
554 a separate component is the need to support legacy equipment.

555 For the top-level device Power component, the Power represents the power to all other
 556 components than the computer controller. Since the controller may be hosting the MTCConnect
 557 *Agent*, it would be impossible to report Power OFF if the controller is off. If network or physical
 558 connectivity to the device is interrupted, the Power **MUST** be considered off.

559 For all other components, the definition of OFF is the component is not connected to the power
 560 source.

561 **5.3.5.1 DataItem types**

- 562 • POWER_STATUS
- 563 • VOLTAGE
- 564 • AMPERAGE
- 565 • WATTS

566

567 **5.3.6 Thermostat**

568 A sensor capable of measuring the temperature of a component. The temperature is always given
 569 in Celsius.

570 **5.3.6.1 DataItem types**

- 571 • TEMPERATURE

572

573 **5.3.7 Vibration**

574 A sensor capable of measuring the vibration of a component.

575 **5.3.7.1 DataItem types**

- 576 • DISPLACEMENT
- 577 • FREQUENCY
- 578 • VELOCITY
- 579 • ACCELERATION

580 **5.4 Cutting Machine Tool Components and Data Items**

581 **5.4.1 Spindle**

582 The spindle is a rotational axis that revolves at high speed and has its speed expressed in
 583 REVOLUTION/MINUTE. The spindle can also have additional data items. Spindle speed has
 584 been specified as a separate data item since it receives special treatment in many applications.
 585 Velocity is used for linear axes other than spindle.

586 **5.4.1.1 DataItem types**

- 587 • SPINDLE_SPEED
- 588 • LOAD
- 589 • DIRECTION
- 590 • TORQUE

591 6 Annotated XML Examples

592 6.1 Simplest Device

593 For the simplest possible device we are modeling a saw that has only a power status (the minimal
594 set of components). To retrieve this information we send the following request to the *Agent*:

595 <http://10.1.23.10/LinuxCNC/probe>

596 The *Agent* responds as follows:

```
597 1. <?xml version="1.0" encoding="UTF-8"?>
598 2. <MTConnectDevices xmlns:m="urn:mtconnect.com:MTConnectDevices:0.9"
599   xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
600   xmlns="urn:mtconnect.com:MTConnectDevices:0.9"
601   xsi:schemaLocation="urn:mtconnect.com:MTConnectDevices:0.9
602   /schemas/MTConnectDevices.xsd">
603 3.     <Header sender="10.1.23.10" bufferSize="100000" creationTime="2008-07-
604     07T23:07:50-07:00" version="0.9" instanceId="1214527986"/>
```

605 Line 3 provides the `instanceId` as a unique number for this run. For this example, the *Agent*
606 does not persist the samples and events, therefore, this number will change every time. The
607 `bufferSize` indicates that this *Agent* is capable of storing 100,000 samples and events.

```
608 4.     <Devices>
609 5.         <Device iso841Class="6" uuid="linux-01" name="LinuxCNC"
610         sampleRate="100.0" id="1">
611 6.             <Description manufacturer="NIST" serialNumber="01"/>
```

612 The above device description includes the unique id and a sample rate of ten times per second.
613 Since there are no telemetry data being collected, once a second is adequate.

```
614 7.         <DataItems>
615 8.             <DataItem type="ALARM" name="alarm" category="EVENT" id="10"/>
616 9.         </DataItems>
```

617 On line 8 we define the catch-all alarm for this device.

```
618 10.        <Components>
619 11.            <Power name="power" id="2">
620 12.                <DataItems>
621 13.                    <DataItem type="POWER_STATUS" name="power" category="EVENT"
622                    id="9"/>
623 14.                </DataItems>
624 15.            </Power>
```

625 As was stated before, the device is only required to have one `Power` component which **MUST**
626 report its status. The `DataItem` on line 13 has an id number of 9. This will allow events
627 responding to this data item to be easily associated. One can also see that this has been

628 categorized as an Event and the application should expect PowerStatus in the Events
629 collection of the ComponentStream.

```
630 16.         </Components>
631 17.         </Device>
632 18.     </Devices>
633 19. </MTConnectDevices>
```

634 6.2 More Complex Example of probe

635 The sample was generated with the following request:

```
636 http://10.1.23.5/LinuxCNC/probe
```

637 The following is an example of a 3 axis mill simulation. The mill has three linear axes and one
638 spindle:

```
639 1.<?xml version="1.0" encoding="UTF-8"?>
640 2. <MTConnectDevices xmlns:m="urn:mtconnect.com:MTConnectDevices:0.9"
641 xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
642 xmlns="urn:mtconnect.com:MTConnectDevices:0.9"
643 xsi:schemaLocation="urn:mtconnect.com:MTConnectDevices:0.9
644 /schemas/MTConnectDevices.xsd">
645 3. <Header sender="10.1.23.5" bufferSize="100000" creationTime="2008-07-
646 07T23:07:50-07:00" version="0.9" instanceId="1214527986"/>
647 4. <Devices>
648 5. <Device iso841Class="6" uuid="linux-01" name="LinuxCNC"
649 sampleRate="100.0" id="1">
```

650 Here we provide the top level container Devices and the information on the Device.

```
651 6.<Description manufacturer="NIST" serialNumber="01"/>
652 7. <DataItems>
653 8. <DataItem type="ALARM" name="alarm" category="EVENT" id="10"/>
654 9. </DataItems>
655 10. <Components>
656 11. <Axes name="Axes" id="3">
657 12. <DataItems>
658 13. <DataItem type="PATH_FEEDRATE" name="path_feedrate"
659 category="SAMPLE" id="11" nativeUnits="PERCENT" subType="OVERRIDE"
660 units="PERCENT"/>
661 14. </DataItems>
```

662 On line 11 we introduce the collection of Axes. The Axes component is a special component that
663 acts as an abstract component as well as a collection. The Axes component contains various data
664 items that have a global context; they are not associated with any one data item, but they go
665 across all axes.

```
666 15. <Components>
```

```

667 16.      <Spindle name="S" id="7">
668 17.      <DataItems>
669 18.      <DataItem type="SPINDLE_SPEED" name="Sspeed"
670 category="SAMPLE" id="18" nativeUnits="REVOLUTION/MINUTE"
671 subType="ACTUAL" units="REVOLUTION/MINUTE">
672 19.      <Source>spindle_speed</Source>
673 20.      </DataItem>
674 21.      <DataItem type="PRESSURE" name="Jet" id="31"/>
675 22.      </DataItems>
676 23.      </Spindle>

```

677 **The spindle component declared on line 16 is the S axis and has spindle-specific data items.**

```

678 24.      <Linear name="X" id="4">
679 25.      <DataItems>
680 26.      <DataItem type="POSITION" name="Xact" category="SAMPLE"
681 id="12" nativeUnits="MILLIMETER" subType="ACTUAL" units="MILLIMETER"/>
682 27.      <DataItem type="POSITION" name="Xcom" category="SAMPLE"
683 id="13" nativeUnits="MILLIMETER" subType="COMMANDED"
684 units="MILLIMETER"/>
685 28.      </DataItems>
686 29.      </Linear>
687 30.      <Linear name="Y" id="5">
688 31.      <DataItems>
689 32.      <DataItem type="POSITION" name="Yact" category="SAMPLE"
690 id="14" nativeUnits="MILLIMETER" subType="ACTUAL" units="MILLIMETER"/>
691 33.      <DataItem type="POSITION" name="Ycom" category="SAMPLE"
692 id="15" nativeUnits="MILLIMETER" subType="COMMANDED"
693 units="MILLIMETER"/>
694 34.      </DataItems>
695 35.      </Linear>
696 36.      <Linear name="Z" id="6">
697 37.      <DataItems>
698 38.      <DataItem type="POSITION" name="Zact" category="SAMPLE"
699 id="16" nativeUnits="MILLIMETER" subType="ACTUAL" units="MILLIMETER"/>
700 39.      <DataItem type="POSITION" name="Zcom" category="SAMPLE"
701 id="17" nativeUnits="MILLIMETER" subType="COMMANDED"
702 units="MILLIMETER"/>
703 40.      </DataItems>
704 41.      </Linear>
705 Lines 24, 30, and 36 define the three linear axes X, Y, and Z respectively. In this example device
706 the Agent is only collecting the actual and commanded positions.
707 42.      </Components>
708 43.      </Axes>

```

709 The Controller is capable of providing the program name, block, and the current line being
710 executed:

```
711 44.         <Controller name="Controller" id="8">
712 45.         <DataItems>
713 46.         <DataItem type="LINE" name="line" category="EVENT" id="19"/>
714 47.         <DataItem type="CONTROLLER_MODE" name="mode"
715         category="EVENT" id="20"/>
716 48.         <DataItem type="PROGRAM" name="program" category="EVENT"
717         id="21"/>
718 49.         <DataItem type="EXECUTION" name="execution" category="EVENT"
719         id="22"/>
720 50.         </DataItems>
721 51.         </Controller>
722 52.         <Power name="power" id="2">
723 53.         <DataItems>
724 54.         <DataItem type="POWER_STATUS" name="power" category="EVENT"
725         id="9"/>
726 55.         </DataItems>
727 56.         </Power>
728 57.         </Components>
729 58.         </Device>
730 59.         </Devices>
731 60. </MTConnectDevices>
732
```

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